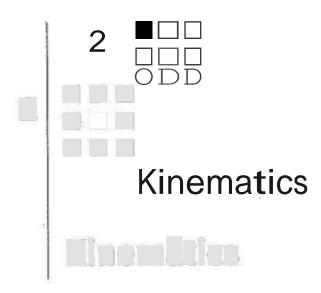
Solution Manual for Active Learning Guide 1st Edition Heuvelen Gentile Heuvelen 032186445X 9780321864451

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1

2.1 Quantitative Concept Building and Testing

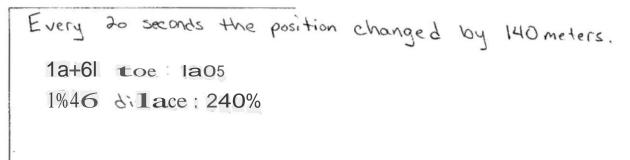
EQUIPMENT

- u Two constant-motion cars that move at different constant speeds (slower with one battery or faster with two batteries)
- O Sugar packets or other small objects that won't bounce
- \Box Metersticks
- \mathbf{W} atch with a second hand
- □ Fancart
- 0 Metal track
- 0 Motion detector
- o Computer
- O Stopwatch
- □ Pulleys
- o Strings
- $\hfill\square$ Small block of about 30–50 g

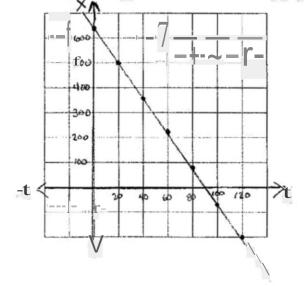
The table indicates yo	ur position al	long the path at	different	clock readings.

 Clock reading t (s)	Position x (m)	
t =0	×%=640	
t = 20	$x_i = 500$	
l,=40	x=360	
t,=60	x%,=220 t =	
80	x,=80	
<i>t</i> , = 100	<i>x</i> ,=60	
 <i>t</i> ,=120	x¢=-200	_

a. Write everything you can about the bike ride and indicate any pattern in the data.



b. Construct a position-versus-clock reading graph for the bike trip.



C. Write a function x() of the graph in part b.

$$X(t) = mt + b$$

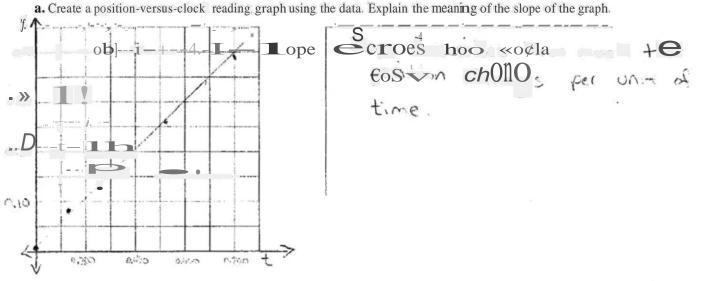
 $X(t) = (-7 + 640m)$

d. What is the physical meaning of the slope of the function and the intercept on the vertical x axis? Explain what it means **if** these quantities are positive or negative.

2.1.2 Observe and describe In the table, we provide data describing a glider moving on an air track.

Clock reading t (s	b) Position x (m)	
t,=0.000	x%=0.01 t,	
=0.133	<i>x</i> ,=0.07	
t,=0.267	<i>x</i> ,=0.13	
t, =0.400	× =0.20	
t,=0.533	x = 0.26 t,	
=0.667	x, -0.33	
t,=0.800	x, =0.39	

activity continues p



b. What common name could you use for the slope?

Velocity or spare

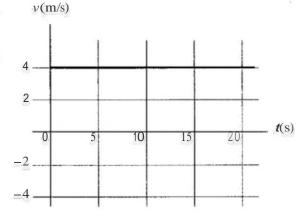
c. Use the graph from part a to write a mathematical function that gives the position of the glider as a function of the clock reading.

X(t) = 0.01 + (0.45 + t)t

d. Would the answers be different if data were taken for the back of the glider?

r Yes, the istal position would be different +kece Ae the x-axis intercept ootd be different.

2.1.3 Analyze The figure at the right shows a velocity• versus-clock reading graph that represents the motion of a bicycle modeled as a point particle moving along a straight bike path. The positive direction of the coordi• nate axis is toward the east



a. Use the graph to estimate the bike's displacement from a clock reading of 10 s to a clock reading of 15 s. Explain.

$$t = 10: \longrightarrow X = V \cdot t = 4\frac{m}{2} \cdot 10s = 40m$$

 $t = 15s \longrightarrow X = 4\frac{m}{2} \cdot 15s = 60m$
 $d = X_{f} - X_{i} = 60m - 40m = \frac{m}{c+Cr}$

b. Use the graph to estimate its displacement from a clock reading of 0 s to 20 s.

$$t - = - x - O_+$$

 $t = O_- >> Y - O_{\%}$
 $d = X_i - X_i = 80_m - O_m = 80_m$

activity continues p

c. Formulate a general rule for using a velocity-versus-clock reading graph to determine an object's displacement during some time interval **if** the object is moving at constant velocity.

2.1.4 Predict and test Gather two motorized cars.

a. For car A, use sugar packets, a meterstick, and a watch with a second hand to design an experiment to decide if the car moves with constant velocity. If it does, determine the magnitude of the velocity (the car's speed). Make a data table to record your measurements.

Drop suga	r packets	at the position	of the	1. 4 f 2	SPUC	clock
reading	s. Use the	meter tick t.	mentine	41. 15	'' ^j 'e' t''(,	1-1 political
2157	Ximi					
0	1 0	X-O+(0.=;	-			
1	0.20					
N C	0.31	V= 0.201				
4	0.82					
5	1.02					

b. For car *B*, use the same equipment as in part a to design an experiment to decide if this car moves with constant velocity. If it does, determine the magnitude of the velocity (the car's speed).

100		
-t &)		X (= 0+/6.5?4=
Ŭ		
a	0.72	V- 0.40 'j
3	`,\q	V- 0.40 "J
!/ <u></u>	(e	
s7	32.00	
C	a_{-}	

1

c. Fill in the table that follows to make your prediction of where the two cars will meet if you release them 2.0 m apart and moving straight toward each other. To make a prediction, use your knowledge of the cars' speeds gathered from parts a and b and the relationship between the initial state, velocity, time elapsed, and the final state of an object.

Experiment	• Write the position-versus- clock reading data for the car. • Write the position-versus- clock reading data for the car.
•Car A	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
• Car B	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
	Predict where the cars will meet. Perform the experiment; record the meeting loca• tion and compare it to your prediction.
	1.=X%
	(p05) =20-0=0 they meet at 0.65m
	(po#)-2.0% Very close to our
	t = 3.33 son producted volue
	X = (0.20 =) (3.33 =)
	X = 0.666 m

2.1.5 Observe and analyze You place a cart on a smooth metal track tilted at a 10° horizontal angle. The data table provided records the position of the front of the cart at different times. The x axis points along the track.

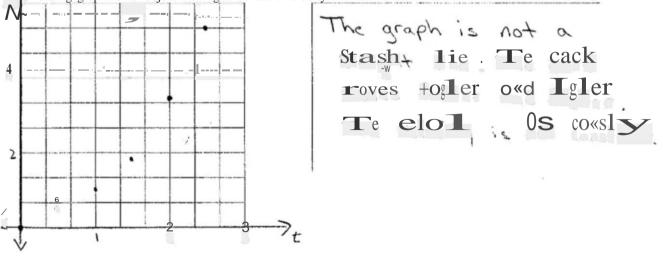
Clock reading $t(s)$	Position x (m)
$t_{,}=0.00$	x¢=0.00
t =0.50	<i>x</i> ,=0.21
t ₂ =1.00	x,=0.85
<i>t</i> , =1.50	x=1.91
t,=2.00	x,=3.40
<i>t</i> , =2.50	<i>x</i> , =5.31

a. Draw a motion diagram for the cart; consider the cart as a particle.

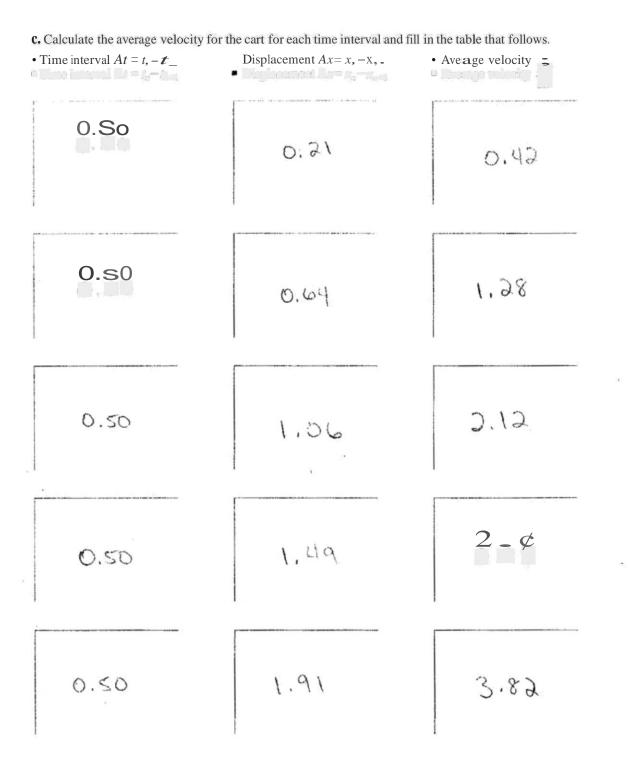


%

b. Draw a position-versus-clock reading graph for the cart. Discuss whether the graph resembles a position-versus-clock reading graph for an object moving at constant velocity.



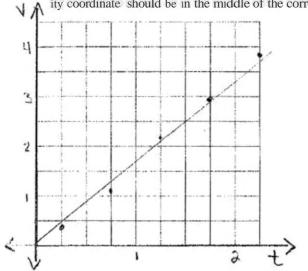
2-8	CHAPTER T	wo	KINEMATICS
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activity continues

CHAPTER TWO KINEMATICS 2-9

d. Plot this average velocity on a velocity-versus-clock reading graph. The clock reading coordinate for each average veloc• ity coordinate should be in the middle of the corresponding time interval. Make a best-fit curve for your graph line.



e. Discuss the shape of the graph: How does the speed change as time elapses? Suggest a name for the slope of the graph.

f. Write an equation for the velocity as a function of a clock reading that is consistent with the graph line. Discuss how your equation would change if you started observing the cart when it was already moving down the same inclined plane. Discuss how the equation would change if the cart was slowing down instead of speeding up. How would it change if it was moving in a different direction?

$$V(t) = 0 + (1.7 \frac{m_s}{s})t$$

$$-J \notin ts \in slot Ael Ogina 4 - 1 Cat d + ke$$

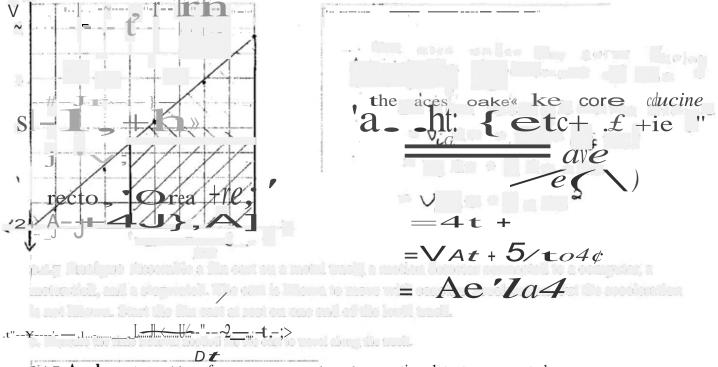
$$le. v = Zac \notin t$$

$$old be areal < r k Ac 28co$$

$$-If the cart were since down the slop \notin slop \notin$$

2-10 CHAPTER TWO KINEMATICS

2.1.6 Derive Use the method developed in Activity 2.I.3 to find a relationship between the displace• ment of the cart described in Activity 2.1.5 during some time interval, its velocity at the beginning of this interval, its acceleration, and the length of the time interval. Start by drawing a velocity-versus-£lock reading graph and examining the area under the graph line.



2.1.7 Analyze Assemble a fan cart on a metal track, a motion detector connected to a computer, a meterstick, and a stopwatch. The cart is known to move with constant acceleration, but the acceleration is not known. Start the fan cart at rest on one end of the level track.

a. Measure the time interval needed for the cart to travel along the track.

I. We the concepts Brack follow for to Statisticate the adoution of the cust, externing that it is a constant.

$$\Delta X = V_1 t + \frac{1}{2} \alpha t^2$$

b. Use the concepts developed so far to determine the acceleration of the cart assuming the tait is constant.

anthin continues (F

activity continues \mathbf{b}

CHAPTER TWO KINEMATICS 2-11

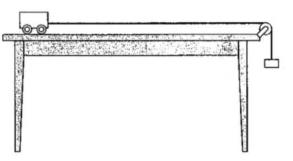
c. Then use the motion detector to measure the acceleration.

2:0.59% M/22

d. Compare the results and account for the differences. Think of the assumptions that you made and experimental uncertainties as a result of your equipment.

Te &+frecce bore Ae ressord on~ calculad vie is within the limits of experimental uncertianties 4 à Caska+ rs%. 4 à Caska+ rs%. 4 à Caska+ rs%. 4 à Caska+ rs%.

2.1.8 Predict and test Place a low-friction cart on a long, smooth table (or you can place a cart on a metal track). Assemble a motion detector connected to a computer, a pulley, a string going over the pulley connected to the cart on one end (see the illustration at the right) and to a small hanging block (an object of about 30–50 g) on the other end. Collect a meterstick and a watch with a second hand.



a. Use the motion detector to find the acceleration of the cart after the hanging block is released. Record it here.

Students can perform the experiment IGC.

2-12 CHAPTER TWO KINEMATICS

June, Conversi The Stream (Converse)

b. Now place a toy motorized car on the right end of the table (you now know its constant speed from Activity 2.1.4). Predict where the car and the cart will meet on the table if you face them directly opposite each other and then release them simultaneously. Use the position-versus-time relationship for constant-velocity motion and for constant-acceleration motion to help you make your prediction.

Motion model le
$$X = 1$$
 et $X = 1$ et X = 1 et $X = 1$ et $X = 1$ et $X = 1$

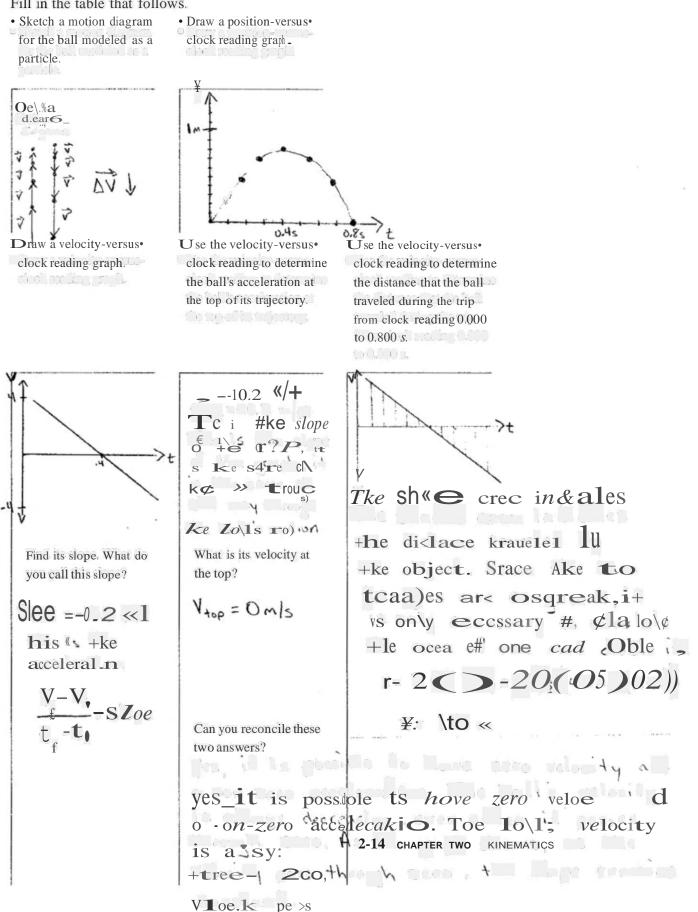
c. After you make your prediction, release the car and the cart and test your prediction. Do the results support your prediction in part b within experimental uncertainties? Explain carefully.

2.1.9 Analyze The data recorded in the completed table are a record of the up and down motion of the center of a ball thrown up into the air (they axis points up).

	100-		and the second second second	The set of		
	Clo	ck 1	reading t (s)	Posit	ion	y (m)
	'0	=	0.000	y0	=	0.00
	<i>t</i> ,	н	0.067	Y	Ξ	0.24
	ť2	=	0.133	\mathbf{v}^2		0.44
	t	=	0.200	Y	=	0.60
	t¢	Ξ	0.267	Y	=	0.71
	<i>t</i> 5	⊒	0.333	ys	=	0.78
	ts	÷	0.400	Y%	Ŧ	0.80
	t	=	0.467	\mathcal{Y}	-	0.77
	ts	=	0.533	ys	=	0.71
	to	Ξ	0.600	<i>y</i> 0	Ξ	0.59
	·10	Ξ	0.667	/10	Ξ	0.42
	t١	=	0.733	11		0.21
	41	=	0.800	/12	=	0.04
-				Contraction in the second		

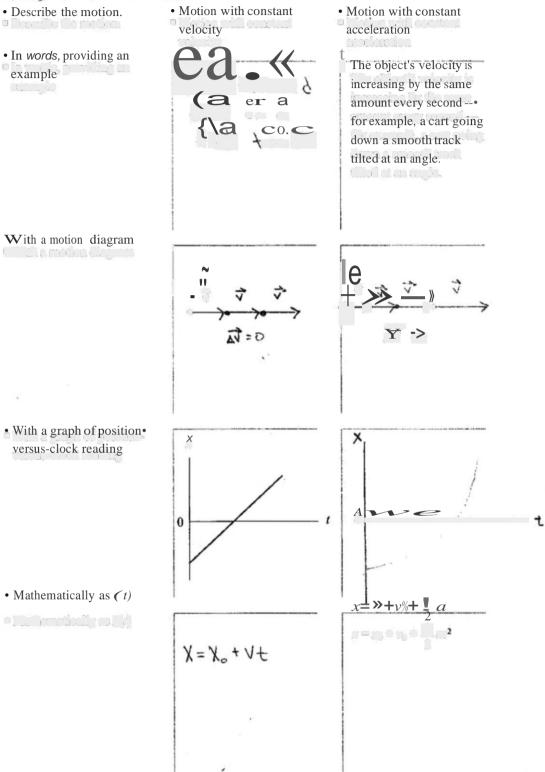
activity continues p»

Fill in the table that follows.



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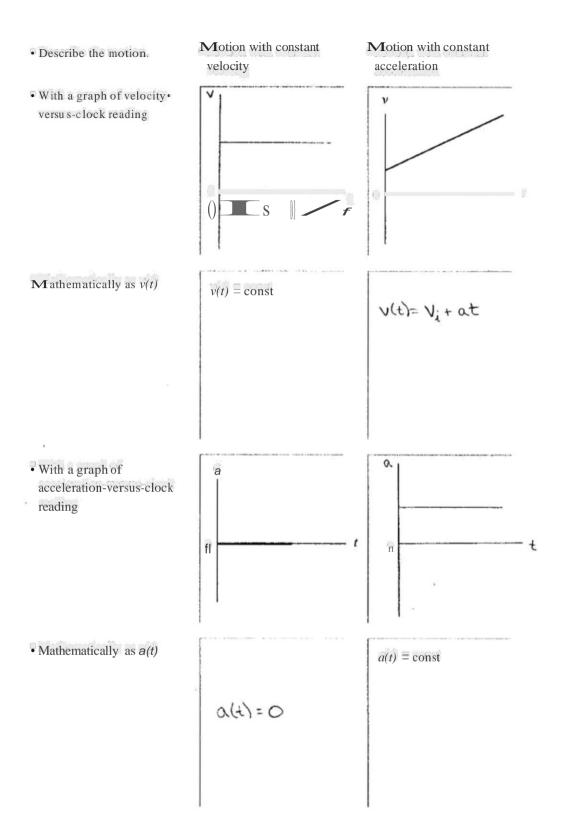
sir ,ever a4'ee ~ po°.-> s Ke areO sous, Os +e co9 zero, e lope re+a5 **2.1.10 Summarize** Analyze the information in the table below and complete the empty cells to sum• marize your knowledge of motion with constant velocity and with constant acceleration, using differ• ent representations of motion.



activity continues b

gabiy coataat (B

CHAPTER TWO KINEMATICS 2-15



2.2 Quantitative Reasoning

EQUIPMENT

- □ Track
- o Low-friction cart
- o Stopwatch
- u Meterstick
- o Cotton balls

Problem-Solving Strategy: Kinematics Problems

PICTURE AND TRANSLATE

- Sketch the situation described in the problem.
- Include a coordinate system and indicate the origin on the sketch.
- Write the known and relevant information as physical quantities on the sketch.

SIMPLIFY

- Decide if you can consider a moving object as a particle.
- Decide whether you have enough information to consider this as motion with constant velocity or with constant acceleration.

REPRESENT PHYSICALLY

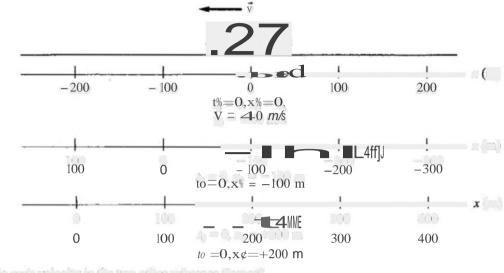
- Decide what physical representation is helpful to solve the problem.
- Draw a motion diagram or if appropriate an x(t), v(t), and/or a(t) graph.

REPRESENT MATHEMATICALLY

• Use your physical representation to construct mathematical representations of the process. Be sure to consider the signs of the velocity and acceleration.

SOLVE AND EVALUATE

• Solve the equations and evaluate the results to see if they are reasonable. To assess for reasonableness, check the units, limiting cases, and the magnitude of the unknown quantity and make sure they make intuitive sense. **2.2.1 Represent and reason** A car moves west at 40 m/s on a straight highway. The car's motion at the time we start describing it is presented in the illustration below using three different reference frames. Note the description in the first reference frame. Answer the following questions.

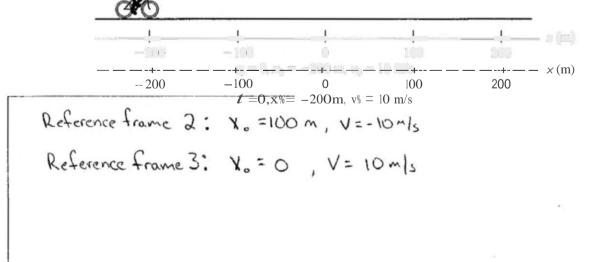


a. Willot is the car's velocity in the two other administre distant

a. White the car's velocity in the two other reference frames? V=40 m/s Reference frame 3: V=-40 m/s

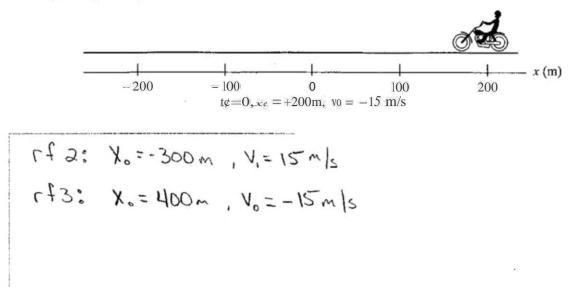
I. It Mayde minite exist it constant specifies the same stallplit shall. The Dispele's intelest is described in the Bastanden Telemat are perfected time using one objectivities system. Bessaille the Repute's location is described in the dame time, A kingele means and at compared on the same training and the kingele's metion is described in the illustration.

b, A bicycle moves east at constant speed on the same straight road. The bicycle's motion is described in the illustration below at one particular time using one coordinate system. Describe the bicycle's location and velocity at the same time, using the last two coordinate systems shown in the illustration for part a.

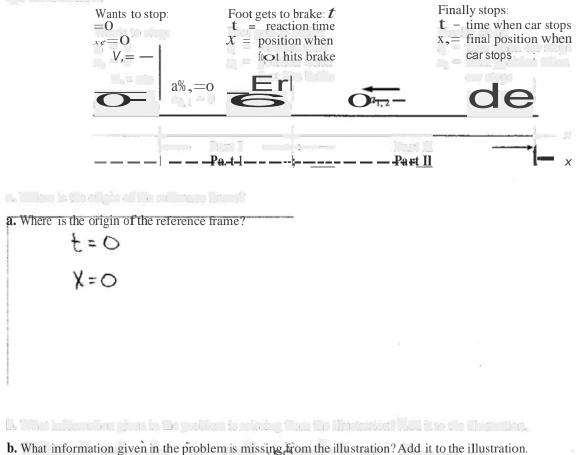


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c. A motorcyclist rides west on the same road at constant speed. Her motion is depicted in the illustration below at one particular time using one coordinate system. Describe her location and velocity at the same time, using the last two coordinate systems given in part a.



2.2.2 Picture and translate The driver of a car moving east at speed vo sees a red light in front of him and hits the brakes after a short reaction-time interval. The car slows down at a rate of $a_{\uparrow} \circ A$ typical reaction time is 0.8 s. The situation is represented in the picture below. Note the details in the illustration.



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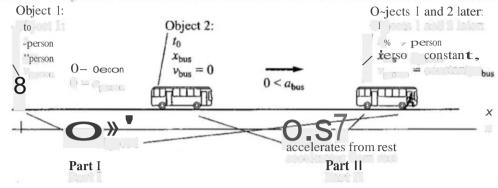
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CHAPTER TWO KINEMATICS 2-19

2.2.3 Picture and translate Assume Jabari is running at a constant speed vo, trying 10 catch a bus that starts at rest and moves with the acceleration **as**.

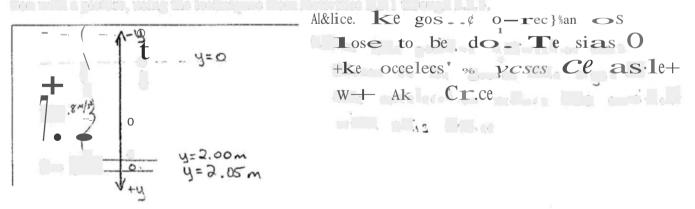
a. The illustration below represents when and where Jabari catches the bus. Note the details in the illustration.



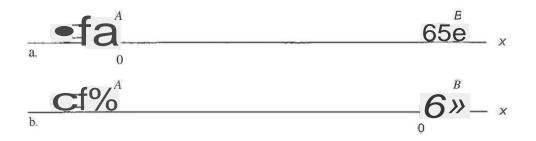
b. What is the reference frame used in the illustration?

	The llwslclion.	S	e	Los	is	sed	4,¢
c	. What information given in the p				ld it to th	e illustration	n.

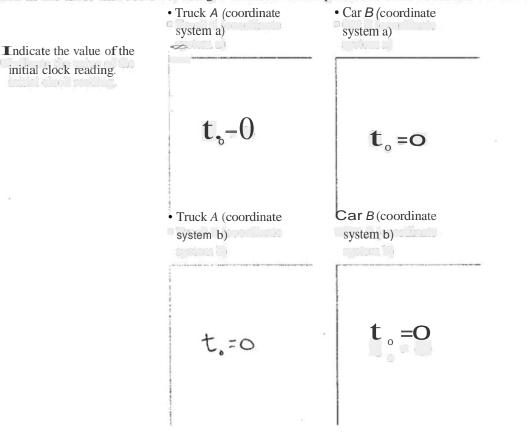
2.2.4 Represent and reason An apple falls from a tree, starting a distance of 2.0 m from the top of the grass. While falling, the apple has a downward acceleration of 9.8 m/s². As the apple sinks into the grass, its speed decreases, until it finally stops after sinking 0.050 m into the grass. Represent this situation with a picture, using the techniques from Activities 2.2.1 through 2.2.3.



2.2.5 Represent and reason Truck A, starting at rest, moves faster and faster toward the east so that its speed increases by 3.0 mis each second. At the same time that truck A begins to move, car B, 200 m east of truck A and moving at speed 16 m/s toward the east, begins to slow down by 1.0 mis each second.

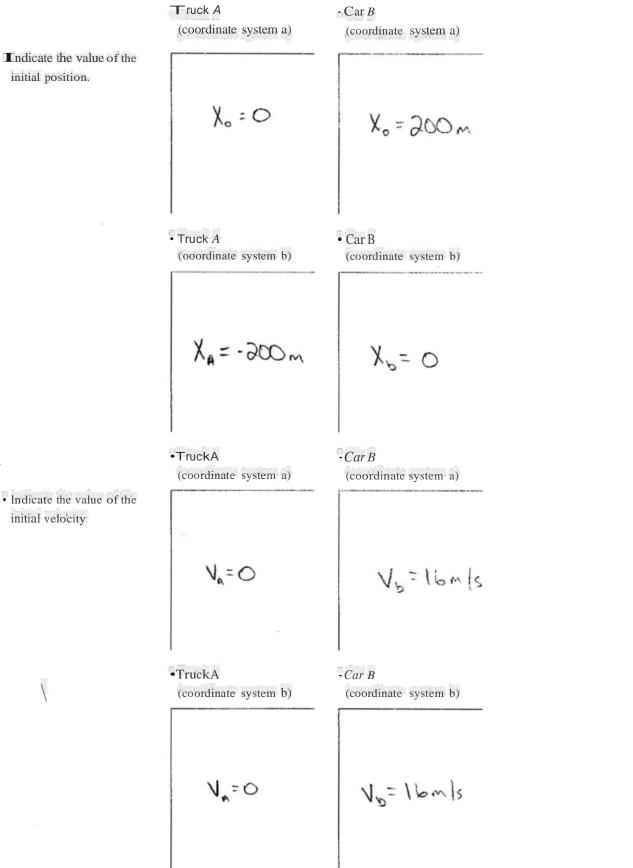


Fill in the table that follows, using a different description for each coordinate axis shown.



activity continues b»

CHAPTER TWO KINEMATICS 2-21



+ Truck A

• Truck A

(coordinate system a)

+Car B (coordinate system a)

a= 3m/s2

(coordinate system b)

Qa= 3m/s2

Car B (coordinate system b)

a = - 1 m/s2

(coordinate system a)

a Truck A (coordinate system a)



Truck A (coordinate system b)

•Car 8

r----

• Car B (coordinate system b)

X(1)= (-200m) + == (3 m/s") t2

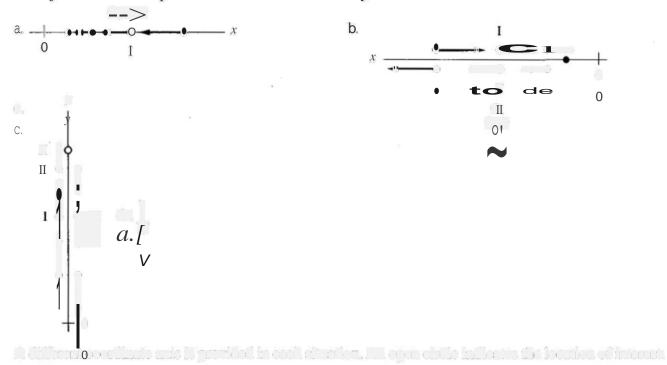
 $x \ll -(u?)b + \frac{1}{2}(-1\frac{m}{2})t^{2}$ $x = (0 - th - \frac{1}{2}t^2)$

X = (20 - (=)L + (-):

e Write equations that can be used to determine the position and velocity of the vehicle at any given

clock reading in the future.

2.2.6 Represent and reason The motion diagrams in the illustrations represent the motion of different ent objects modeled as particles. The arrows are velocity arrows.



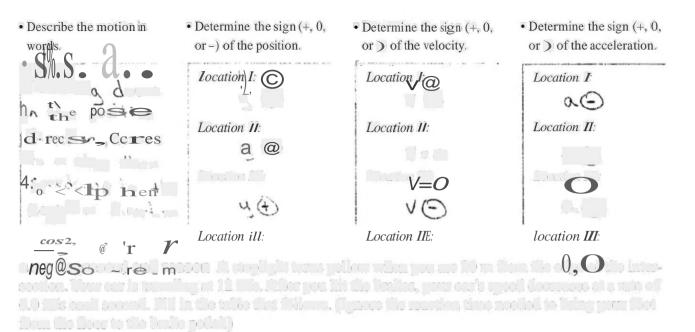
A different coordinate axis is provided in each situation. An open circle indicates the location of interest.

a. Draw acceleration arrows on each diagram above.

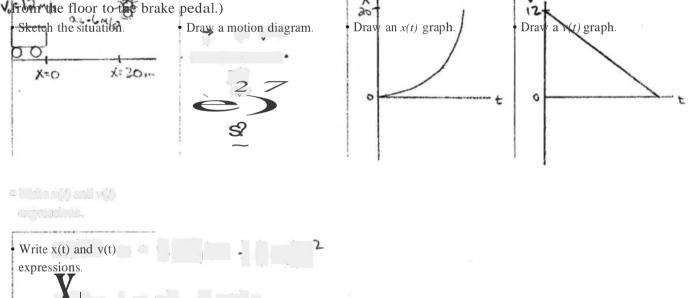
b. Fill in the table that follows. Be sure to make your choices relative to the coordinate axis shown in each motion diagram.

• Describe the motion in • Determine the sign (+,0, • Determine the sign (+, 0,• Determine the sign (+, 0,or) of the velocity or –) of the acceleration. words. or --) of the position. Location I: a. Location I: Location I: Slenc dco» X (+) V(-) a(f is +he edle dcec\ion Location I: Location I: Location 516«g dos x 6 a n +he oegetive Location A Location IA Location rec\vs. cores to a sop en Sped of is W DC-e C**C**

2-24 CHAPTER TWO KINEMATICS



2.2.7 Represent and reason A stoplight turns yellow when you are 20 m from the edge of the intersection. Your car is traveling at 12 m/s. After you hit the brakes, your car's speed decreases at a rate of 6.0 *mis* each second. Fill in the table that follows. (Ignore the reaction time needed to bring your foot



6+(S - 4(5) v@-(25)-(5)¢

CHAPTER TWO KINEMATICS 2-25

2.2.8 Represent and reason You ride your bike west at a speed of 8.0 mis. Your friend, 400 m east of you, is riding her bike west at a speed of 12 mis.

a. Fill in the table that follows. (Consider the bikes as particles.)

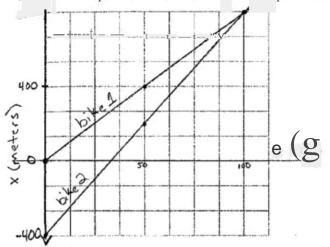
PICTURE AND TRANSLATE • Draw a sketch of the initial situation VEIZMIS V= 8mls and choose a coordinate system to describe the motion of both bikes. ÷Χ -x XTO 400 (meners) REPRESENT PHYSICALLY (ke δ_ • Draw a motion diagram for each bike. € REPRESENT MATHEMATICALLY • Construct equations that describe the =X.+vt GXCD = X.+Vt positions of each bicycle as a function of time. (0=(2))¢ x«)- -0a _ (35)% SOLVE AND EVALUATE Y.**=¥** Ves, beco9se ry • Use the equations to determine when the bicycles are at the same position. Tend +rue'Za **_-**(1) Does your result make intuitive sense? is Ca.ke + <ksl} 4co.=(a3)t-Z) loo < csds !s be COp '0K H٦ CC«ts«ce 44 100 M t = 100 sec

?at

Des inte

2-26 CHAPTER TWO KINEMATICS After you fill in the table, complete the following:

- Draw a position-versus-clock r~din — ph for each bicycle using the same set of axes.



c. Are the slopes of the two lines and their initial values consistent with the actual motion and the coordinate system used to describe the motion?

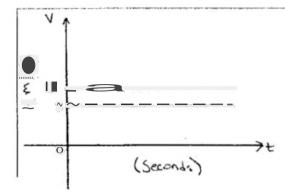


d. Does the appearance of the graph correspond to the calculated answer for the time when the bicycles are at the same position? Explain.

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activity continues \mathbf{p}

e. Draw a velocity-versus-time graph with lines representing the velocity of each bicycle.



f. Are the signs consistent with the word description of the motion?

VeS, I rae pssiwe vlo becsose ke on is < r ke posty Y-Adrecha

2.2.9 Represent and reason An object moves horizontally. The equations below represent its motion mathematically. Fill in the table that follows to indicate actual motion that these two equations *together* might describe.

$a_v = +20 \text{ m/s} + (-2 \text{ m/s})$

b. $r = -200 \text{ m} + (+20 \text{ m/s})t + (1/2)(-2 \text{ m/s})^2$

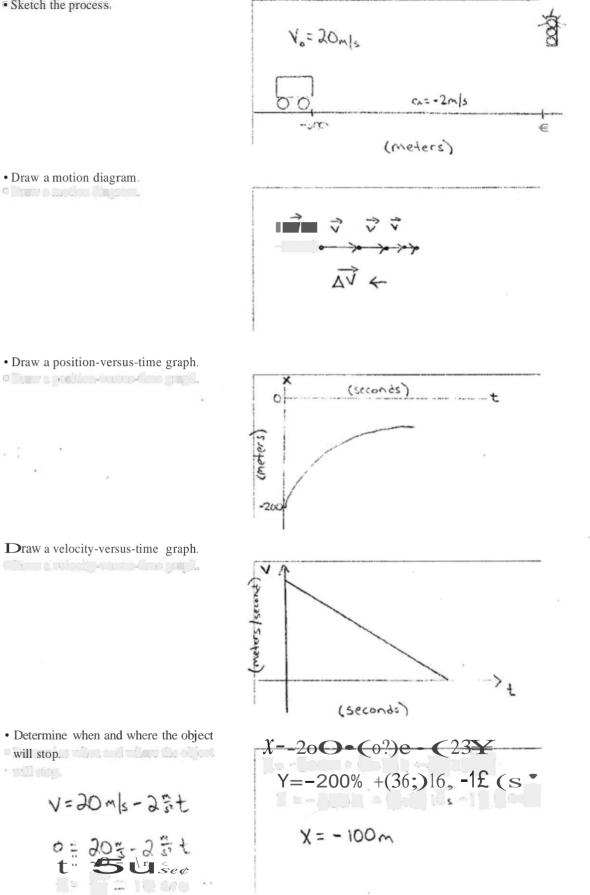
• Describe the motion in words.

 $J_0 = dO m Is$ $\alpha = -2 m Is^2$ $X_0 = -200 m$

d cos is oploach s St +r6ale at ootis. 200 meters be!'re 4he gs+ i+ begins to slow down at o cale a°

2-28CHAPTER TWOKINEMATICS8-08COLORED TWOCOLORED TWO

• Sketch the process.



CHAPTER TWO	KINEMATICS	2-29
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2.2.10 Regular problem While traveling in your car at 24 m/s, you find that traffic has stopped 50 m in front of you. Will you smash into the back of the car stopped in front of you? Your reaction time is 0.80 s and the magnitude of the car acceleration is 8.0 m/s after the brakes have been applied. List all the assumptions you make.

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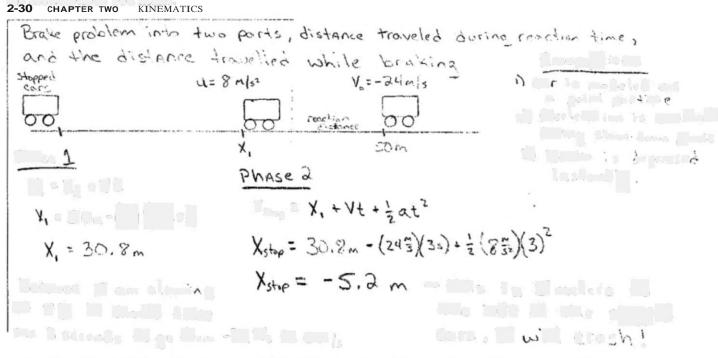
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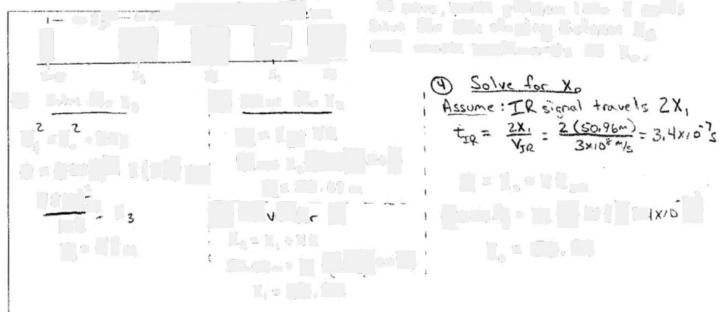
2.2.11 Regular problem Your summer job is with an automobile accident avoidance research team. The system they are investigating sends out infrared radiation from an avoidance device in the car. The infrared signal reflects from an object in front of the car and returns to the avoidance device. The device measures the time delay and is able to process the signal in 0.010s. If a hazard is indicated, the signal causes the car's brakes to be applied in another 0.060 s. The car can slow to a stop with an acceleration of 8.0 m/s^2 . Determine the shortest distance to a stationary object on the freeway that can be avoided with

this device if the car is traveling at 28 mis (63 mph). Infrared radiation travels at a speed of 3.0 \times 10 m/s.

z.s. an Englador problem. While torouting to grant 24 Min, gost 2011 this totals. The stopped 50 m. In Next of yes. Will yest second into the back of the car stopped in first of yes? These repetien time is 0.00 s and the magnifule of the car acceleration is 3.4 MMR after the failies have been nyphed. Bit all



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2.2.12 Regular problem During a heated conversation, you step backward off a 1.2-m ledge. You land stiff-legged and stop in 0.020 m. Determine your speed just before reaching the floor and your acceleration while stopping. What assumptions did you make? Can you model yourself as a particle to solve this problem?

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2.2.13 Regular problem The fuel in a bottle rocket burns for 2.0 s. Will burning, the rocket moves upward with an acceleration of 30 m/s².

4. What is the vertical distance traveled while the fuel is still burning, and how fast is it traveling at the end of
$$e$$
 burn?
4) - $ea_{a=30\%} = (\sqrt[7]{-90}) - go$
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b. After the fuel stops burning, the rocket continues upward but with a velocity dccrcasing at a rate of about 10 M/S. Estimate the maximum height that the rocket reaches. What assumptions have you made while working through this problem?

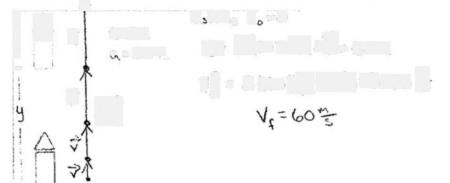
$$A = \frac{S^{-}}{7} = \frac{10}{3}$$

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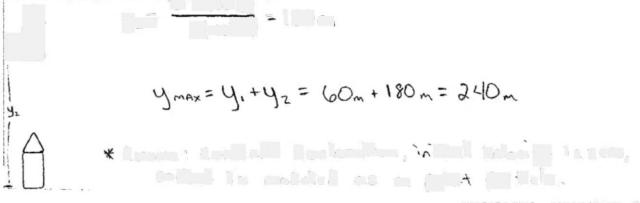
Lize O Speed concer reaching floor Assumptions: bissorre' Contant (all of a grant of a Ŷ V CHAPTER TWO KINEMAIS 2-31 (2) Acceleration while stopping - i a AV. $A = \frac{0 - (4.85 \frac{2}{3})^2}{2(0.02m)} = -588 \frac{m}{s^2}$ + xet I found the acceleration while stopping to be land to be subled to be sold to be

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2.2.14 Regular problem While concentrating on catching the football, a wide receiver on a football team runs into the goalpost. He was originally moving at 10.0 m/s and bounced back at 2.0 *mis*. A video of the collision indicates that it lasted 0.020 s. Determine the acceleration of the receiver during the collision. Indicate any assumptions you made. How will you model the receiver to solve the problem?

2.2.15 Evaluate the solution

The problem: A firefighter slides a distance of 2.0 mat increasing speed for 2.0 s down a firepole (she holds on so she doesn't move too fast at the bottom). She bends her knees at the bottom and stops in 0.10 m. Determine her speed at the end of the slide and just before she contacts the floor. What is her acceleration while stopping?

Proposed solution:

 $v = v^{\%} + at = 0 + (9.8 \text{ m/s})(2.0 \text{ s}) = 19.6 \text{ m/s}$ $a = (-v)/2(x - x^{\%}) = [0 - (19.6 \text{ m/s})]/2(0.10 \text{ m}) = -1920.8 \text{ m/s}?$

a. Identify any errors in the solution.

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$$tepp(Q_{1}^{2}, y_{0}^{2})$$
; $\frac{1}{2(x-x_{0})} = \frac{20^{n}/s^{2}}{2(-0.10 > 2)}$

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2-32 CHAPTER TWO KINEMATICS

b. Provide a corrected solution if there are errors.

Acceleration while stopping:

$$\alpha = \frac{v_{r}^{2} - V_{r}^{Z}}{2(-Y_{r})^{2}} = \frac{0 - (-20\frac{M}{2})^{2}}{2(-0.10m)} = 20^{M}/s^{2}$$

2.2.16 Evaluate the solution

The problem: You are driving at 20 *mis* and slam on the brakes to avoid a goose walking across the road. You stop in 1.2 s. How far did you travel after hitting the brakes? *Proposed solution:*

 $(x-x) \neq vi \equiv (20 \text{ m/s})(1.2 \text{ s}) \equiv 24 \text{ m}$

a. Identify any missing steps and/or errors in the solution.

a. Deathly any advalue stops and let envey in the solution.

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b. Provide a corrected solution if there are missing steps and/or errors.

2.2.17 Design an experiment You have a track tilted at a small angle, a toy car (not motorized), a stopwatch, and a meterstick.

a. Describe in detail an experiment that you can use to determine if the car moves at constant speed, constant acceleration, or changing acceleration along the track.

T order O delecci«e +1e type cno\ion ke to coc ex.it: oe ill creole c le:lole hypothesis. Or \mathfrak{S}^{r} ape@seat.ue ill Skork +e car+ ot severe l Geres | post-sos oleo #le Cac ad oeos0re Rue kce skes O reock Le be\-+ow, Ten We co plot ke : Ar~ir' (o+w verse: clock reeding leer prop oples conscone velecrtg d-a porkolc irpls **b.** Sketch the apparatus. Write on the sketch what you will measure and what you wil'calculate. CO»Ste»t> accelercrt z.

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e. List experimental uncertainties and how you will minimize them.

Tere Me once - g in boll quallies «e easoG; +le dictance owd e clock (eedo. e o winize lke by performing MANY trails. d. Perform the experiment; record the data in a table and use a best-fit function for the data to make a judgment.

Students should perform the experiment an include their data

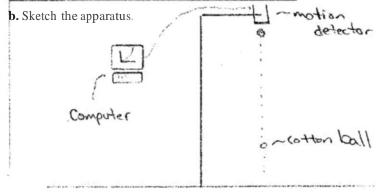
e. Write your judgment about the car's motion.

Te daa. suppor 1 + le Coos an + ace $eco \pm ea$ Odel \$ 015a.

2.2.18 Design an experiment You have a cotton ball, a stopwatch, and a meterstick.

a. Describe in detail an experiment that you can perform to determine whether the cotton ball falls with constant acceleration or changing acceleration.

6 AC eypeG>>et tes use a motion detector connected be $o C \leq gtec$ He plot $\mathbb{I}e$ go&risn uk kcae., and +keVekc e Ace. Ue $co \ll e \in R \pm 0$ tea geiclias Kr each ess 1e 49ype > «1sn.



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CHAPTER TWO KINEMATICS 2-35

c. Write the physical quantities that you will measure and the quantities that you will calculate.

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d. List experimental uncertainties and how you will minimize them.

The cre uncertainties in the postion On clos reading voec c_{-} at Te Gii «size them use can increase le nu «oec 1, es/lech - \leq So that more data is taken.

C Declem the organization and the data in a table and use a best-fit function for the data to make a judgment. **e.** Perform the experiment; record the data in a table and use a best-fit function for the data to make a judgment.

Students will F the experiment

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f. Write your judgment about the ball's motion.